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XGC75T伸缩臂履带起重机

XGC75T Telescopic Crawler Crane

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技术性能参数/整机基本尺寸 Technical Specification/Overall Dimension

详细介绍 Brief Introduction

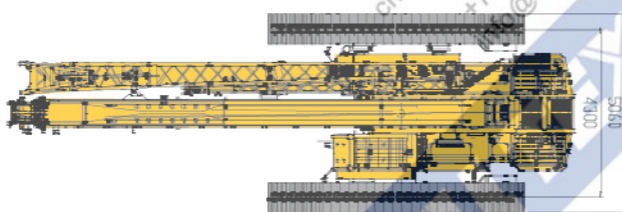
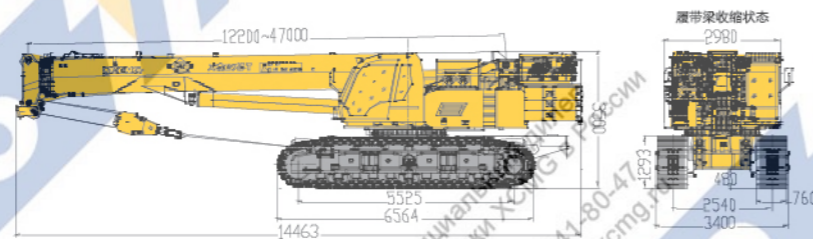
XGC75T

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类别Category	项目Items	单位Unit	参数Data	
尺寸参数 Dimension	整机全长 Overall length	mm	14463	
	整机全宽(伸/缩) Overall width (extension/retraction)	mm	5060/3400	
	整机全高 Overall height	mm	3500	
	主、从动轮中心距 Central distance from drive roller to driven roller	mm	5525	
	履带板宽 Track shoe width	mm	760	
重量参数 Weight	行驶状态总质量 Total mass in travel state	kg	79888	
	空载行驶速度 Max. travel speed with no load	km/h	2.5	
行驶参数 Travel	满载行驶速度 Max. travel speed with full load	km/h	1.5	
	最小离地间隙 Min. ground clearance	mm	480	
	最大爬坡能力 Max. grade-ability	%	40	
	接地比压 Ground pressure	MPa	0.096	
	发动机型号 Engine model	-	潍柴 WP7.270	
动力参数 Power	发动机额定功率 Engine rated output power	kW	199	
	发动机额定转速 Engine rated rotation speed	r/min	2000	
	发动机排放标准 Engine emission standard	-	非道路三阶段	
	液压油箱容积 Hydraulic oil tank	L	1000	
容积参数 Capacity	燃油箱容积 Fuel tank	L	550	
	最大额定总起重量 Max. rated lifting capacity	t	75	
主要性能参数 Main performance	最小额定幅度 Min. rated working radius	m	3	
	最大起重力矩 Max. load moment	基本臂 Base boom	kN·m	2764
		最长主臂 Max. length boom	kN·m	1443
	起升高度 Lifting height	基本臂 Base boom	m	11.6
		最长主臂 Max. length boom	m	46
		最长主臂 + 副臂 Max. length boom + Jib	m	62.1
	起重臂长度 Boom length	基本臂 Base boom	m	12.2
		最长主臂 Max. length boom	m	47
		最长主臂 + 副臂 Max. length boom + Jib	m	64.5
	副臂安装角 Jib offset angle	°	0°、15°、30°	
工作速度 Working speed	主臂起臂时间 Boom raising time	s	60	
	主臂全伸时间 Boom full extension time	s	110	
	最大回转速度 Max. slewing speed	r/min	2.0	
	起升速度(空载四层) Hoisting speed (no load at the 4th layer)	主起升机构 Main winch system	m/min	140
		副起升机构 Auxiliary winch system	m/min	90

本印刷品所包含的数据,会随着产品的不断升级而改变,请以实际产品为准
Pictures and data in this catalog will change with the update and modification of products, so please take the actual vehicle as reference.



上车

发动机

1. 发动机
潍柴WP7.270发动机
额定功率/转速: 199kW/2000rpm
燃油箱: 有效容积550L。

起升机构

起升机构描述:
空载起升速度: 0 ~ 140m/min
钢丝绳直径/长度:
主卷钢丝绳: 20mm/240m
副卷钢丝绳: 20mm/150m
额定单绳拉力: 7.1t

变幅机构

变幅机构描述: 单缸前支变幅
主臂起升时间 ≤ 60S

回转机构

回转机构布置于转台右前端, 由马达驱动。
行星减速机与回转支承齿轮外啮合进行回转, 具有自动滑转功能, 可调整臂架起重作用线与重物同铅直线, 保证作业安全。行星齿轮减速机具备常闭、片式制动器工作可靠维修方便。
回转支承: 采用单排四点接触球式回转支承, 承载能力强, 保证上车360°回转作业安全、平稳。
回转速度: 0 ~ 2.0r/min

电气控制系统

采用 ECU 控制器, 油门门, 手油门, 通过 CAN 实现对发动机转速的高效控制。
系统采用供电方式为 DC 24V, 负极搭铁单线制。采用 PLC 可编程控制器作为控制系统的核心, 系统由发动机控制、安全控制、先导控制、力矩限制器控制、辅助功能控制等几部分组成。通过显示器实时监测发动机水温、机油压力, 当超过安全临界值时, 蜂鸣器自动报警; 同时, 通过力限制器对当前工况的分析, 当吊重量、仰角或幅度任一值超出安全范围时, 三色报警灯和蜂鸣器会发出“声光报警”并通过程序控制, 限制危险动作的进行。

液压系统

液压先导控制, 控制精准, 微动性好, 调速范围广。起重作业伸缩、变幅及起升液压系统与行驶作业液压系统共用一恒功率 L8VO140 双泵, 回转系统 8ml/r 的齿轮泵供油。
采用成熟可靠的液压元件, 成熟稳定的液压传动控制技术。操作简单, 维修维护方便。与电气系统相配合, 保证主机安全稳定。

Crane Superstructure

Engine

Weifang Diesel WP7.270,
rated power / speed: 199kW/2000rpm.
Fuel tank: effective capacity 550L.

Hoist winch

Hoist winch description:
Hoisting speed with no load: 0 ~ 140m / min.
Wire rope diameter / length:
Main winch rope: 20mm/240m.
Auxiliary winch rope: 20mm/150m.
Rated single line pull: 7.1t.

Luffing winch

Luffing winch description: single cylinder front support luffing
Boom raising times ≤ 60S

Slewing unit

Slewing gear is on the left of the behind of turntable and driven by motor.
The planetary reducer is meshed with slewing bearing outer gear, hydraulic buffering, with free swing function to ensure operation safety. There is constant closed, disk-type brake for reliable operation and easy for maintenance.
Slewing gear: 4-row column outer slewing gear, with strong bearing capacity, ensuring superstructure 360° swing operation safe and reliable.
Swing speed: 0 ~ 2.0r/min


Electric control system

Use of ECU controller, foot accelerator, hand accelerator, efficient control of the engine speed by CAN. The system uses DC 24V for power supply, negative ground and single cable system. PLC programmable controller is used as the core of the control system, the system consists of several parts such as engine control, safety control, pilot control, load moment limiter control, auxiliary function control. Real-time monitoring through the display of engine temperature, oil pressure, buzzer warning when the load exceeds the safety limit; at the same time, analysis of current conditions such as lifting load weight, boom elevation angle or radius through load moment limiter, if any values exceed safe limits, a three-color warning light and buzzer will give "sound and light warning", and control and restriction of hazardous actions by program control.

Hydraulic system

The hydraulic system adopts electronic-proportional valve control, featuring precise control, excellent fine movement and wide speed range. The hydraulic system of telescoping, luffing, hoisting and travel operation shares the same L8VO140 double pump; swing system adopts closed type pump; and the pilot system gets oil supply from gear pump of 8ml/r displacement.

The hydraulic system adopts mature and reliable hydraulic components and fluid drive control technology, featuring easy operation and maintenance; it combines with electrical system to ensure safety and reliability.

 下车

下车包括车架、履带行走装置。车架和履带架采用插入式连接，销轴固定。

履带伸缩

通过履带伸缩油缸实现履带架的扩张与收缩。方便转场及狭窄环境通过。

行走装置


有行走马达、减速机、驱动轮来实现整机的直线行走及转弯。空载行驶速度为0~2.5 km/h，带载行驶速度为0~1.5 km/h。

吊钩

名称	75t吊钩	55t吊钩	7t吊钩
重量 (Kg)	700	470	150
数量	1	1	1
备注	标配	标配	标配

平衡重

平衡重由上车平衡重与中央平衡重两部分组成。上车平衡重重量为22.5t；中央平衡重由1块1.1t组成。

 安全装置

安全装置包括急停开关、先导控制开关、力矩限制器、起升高度限制器、水平仪、回转锁止装置、三圈保护器等。

紧急停止

按下急停开关，发动机熄火，整车动作停止。

 Crane Undercarriage

Crane carrier comprises car-body,crawler track and travel gear.Car-body and crawler are using the piug-in connection.

Track frame extension/retraction

retraction is achieved by track frame telescopic cylinder, facilitate site transition and narrow environment through.

Travel device

It realizes crane straight travel and steer through travel motor, reducer and drive roller. Travel with no load speed: 0 ~ 2.5km/h; Travel with load speed: 0 ~ 1.5 km/h

Hook block

Name	75t hook block	55t hook block	7t hook block
Weight(kg)	700	470	150
Qty.	1	1	1
Remark	standar	standard	standard

Counterweight

Counterweight system consists of superstructure and undercarriage counterweight. The superstructure counterweight total 22.5t; the undercarriage counterweight consists of two 1.1t counterweight slabs. The undercarriage counterweight must be installed during operation, and the superstructure counterweight is installed according to lifting capacity and boom length.

 Safety Devices

Safety devices comprise emergency stop switch, pilot control switch, load moment limiter, hoist limit switch, level meter, slewing locking device, rope-end limiter, etc.

Emergency stop switch

Press the emergency stop switch to stop the engine, and to stop all the machine movements.

先导控制开关

按下开关后，起重作业电气系统才能正常操作。

力矩限制器

当吊重量大于额定起重量，吊臂仰角超出额定范围时，或幅度超出额定范围时，力限制器会发出信号，限制危险动作的继续进行。

起升高度限位器

由主、副臂端部限位开关和重锤构成，当吊钩中心起升至距吊臂滑轮中心约710mm时，起升动作自动停止。

水平仪

转台内部、回转支承上方装有水平仪，监控地面是否满足作业要求。

回转锁止装置

保证运输时转台有效锁止，防止其自由滑转。

三圈保护器

当吊钩下降至卷扬钢丝绳剩余三至五圈时，落钩自动停止。

Pilot control switch

Press the switch, the electric system for lifting operation starts to a normal work.

LMI

The LMI will send our alarm signal to prevent dangerous movement when the lifting capacity exceeds the rated capacity, boom angle exceeds rated area or radius exceeds rated area.

Hoist limit switch

It consists of boom and jib end limit switch and the weight, which will automatically stop the hoisting movement when hook block center is raised 710mm to boom sheave center.

Level meter

A level meter is set inside the turntable and on the top of swing,to monitor the ground surface for operation requirements.

Slewing locking device

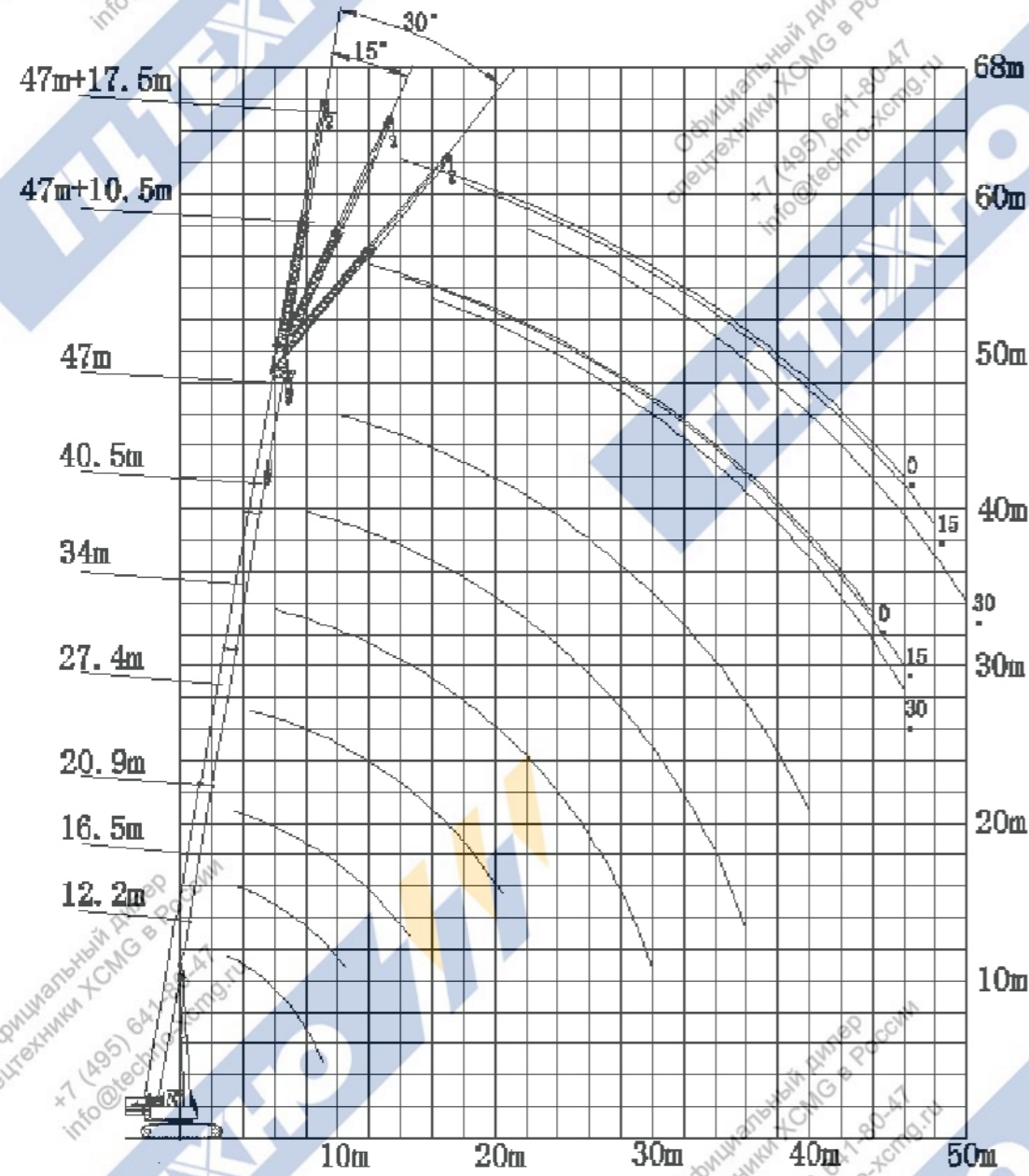
The device is used to lock the turntable during transport to avoid free swing.

Rope-end limiter

The device is used to stop hook block lowering when the hook block lowering down and only three to five turns of wire rope left on the winch drum.

起重工况作业范围图 Lifting Operation Range

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起重工况性能表 Lifting Performance Table

XGC75T

(1) 履带全伸, 配重22.5t, 静止吊重, 360° 作业

履带全伸, 配重22.5t, 静止吊重, 360° 作业							
主臂长度 副臂角度	12.2	16.5	20.9	27.4	34	40.5	47
3	75						
4	68	61	42				
5	56.4	55	42				
6	40.5	46.7	39.0	27.5			
7	31.1	34.8	34.5	27.5	22		
8	24.8	27.3	27	26	20	17	
9	20.4	22.1	21.9	23.8	20	15.8	
10		18.4	18.1	19.9	19	15.2	11.5
12		15.5	15.3	16.9	14.2	14.7	10.5
14		11.3	11.2	12.7	11.1	11.5	10
16			8.5	9.8	8.8	9.2	9.5
18			6.4	7.8	7.1	7.5	7.8
20				6.2	5.8	6.2	6.5
22				5	4.8	5.2	5.4
24				4	3.9	4.3	4.6
26					3.2	3.6	3.9
28					2.6	3	3.2
30					2.1	2.5	2.7
32						2	2.3
34						1.6	1.9
36						1.3	1.5
38							1.2
倍率	12	10	7	5	4	3	3
最大仰角	68.7	73.4	74.8	77.3	78.1	79.5	79.3
最小仰角	25.4	42.8	40.1	37.3	21.6	22.7	35.3

(2) 履带全伸, 配重15.5t, 静止吊重, 360° 作业

履带全伸, 配重15.5t, 静止吊重, 360° 作业							
主臂长度 副臂角度	12.2	16.5	20.9	27.4	34	40.5	47
3	75						
4	68	61	42				
5	47	55	42				
6	33.4	38.7	38.4	27.5			
7	25.5	28.6	28.3	27.5	22		
8	20.2	22.2	22	23.2	21	17	
9	16.5	17.9	17.6	18.8	17.8	15.8	
10		14.7	14.5	15.6	15	15.2	11.5
12		12.3	12.1	13.1	11	11.5	10.5
14		8.7	8.6	9.7	8.4	8.8	9.1
16			6.3	7.3	6.5	7	7.3
18			4.6	5.6	5.2	5.6	5.8
20				4.3	4.1	4.6	4.8
22				3.3	3.3	3.6	3.9
24				2.5	2.6	2.9	3.2
26					2	2.3	2.6
28					1.5	1.8	2.1
30					1.1	1.4	1.7
32						1	1.3
倍率	12	10	7	5	4	3	3
最大仰角	68.7	73.4	74.8	77.3	78.1	79.5	79.3
最小仰角	25.4	42.8	40.1	37.3	21.6	36.2	47.6

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起重工况性能表 Lifting Performance Table

履带全伸, 配重8.5t, 静止吊重, 360°作业

履带全伸, 配重22.5t, 静止吊重, 360° 作业							
主臂长度 副臂角度	75	16.5	20.9	27.4	34	40.5	47
3	60.5						
4	37.5	61	42				
5	26.4	46	42				
6	19.9	30.6	30.3	27.5			
7	15.6	22.4	22.1	23.5	21.4		
8	12.6	17.2	16.9	18.2	17	17	
9		13.6	13.4	14.6	13.3	14.3	
10		11	10.8	11.9	11.5	12	11.5
12		9	8.8	9.9	8.3	8.7	9
14		6.1	6	7.1	6.2	6.6	6.9
16			4.1	5.1	4.6	5	5.3
18			2.7	3.7	3.5	3.9	4.1
20				2.7	2.6	3	3.2
22				1.9	1.9	2.3	2.5
24				1.2	1.3	1.7	1.9
26						1.2	1.5
28	12						1
倍率	68.7	10	7	5	4	3	3
最大仰角	25.4	73.4	74.8	77.3	78.1	79.5	79.3
最小仰角		42.8	40.1	37.3	43.2	49.8	54.3

起重工况性能表 Lifting Performance Table

XGC75T

(2)、臂端滑轮工况, 履带全伸, 静止吊载 (不行走)

履带全伸, 配重22.5t, 静止吊重, 360° 作业							
主臂长度 副臂角度	12.2	16.5	20.9	27.4	34	40.5	47
3	6.5						
4	6.5	6.5	6.5				
5	6.5	6.5	6.5				
6	6.5	6.5	6.5	6.5	6.5		
7	6.5	6.5	6.5	6.5	6.5	6.5	
8	6.5	6.5	6.5	6.5	6.5	6.5	6.5
9	6.5	6.5	6.5	6.5	6.5	6.5	6.5
10		6.5	6.5	6.5	6.5	6.5	6.5
12		6.5	6.5	6.5	6.5	6.5	6.5
14		6.5	6.5	6.5	6.5	6.5	6.5
16			6.5	6.5	6.5	6.5	6.5
18			6.4	6.5	6.5	6.5	6.5
20				6.2	5.8	6.2	6.5
22				5	4.8	5.2	5.4
24				4	3.9	4.3	4.6
26					3.2	3.6	3.9
28					2.6	3	3.2
30					2.1	2.5	2.7
32						2	2.3
34						1.6	1.9
36						1.3	1.5
倍率				1			
最大仰角	68.7	73.4	74.8	77.3	78.1	79.5	79.3
最小仰角	25.4	42.8	40.1	37.3	21.6	22.7	35.3

3)、副臂工况, 履带全伸, 静止吊载 (不行走)

履带全伸, 配重22.5t, 静止吊重, 360° 作业							
主臂长度 副臂角度	12.2	16.5	20.9	27.4	34	40.5	47
3	75						
4	46	61	34.1				
5	28	34.5	34.1				
6	19.4	22.6	22.3	23.9			
7	14.4	16.2	15.9	17.3	15.8		
8	11	12.1	11.9	13.1	12.4	12.9	
9	8.6	9.4	9.1	10.3	9.9	10.4	
10		7.3	7.1	8.2	8.1	8.6	8.9
12		5.8	5.6	6.7	6.7	6	6.3
14		3.6	3.4	4.5	3.9	4.3	4.6
16			2	2.9	2.5	3.1	3.4
18				1.9	1.8	2.2	2.4
20				1	1.1	1.5	1.7
22						1.2	1.2
倍率	12	10	7	5	4	3	3
最大仰角	68.7	73.4	74.8	77.3	78.1	79.5	79.3
最小仰角	25.4	42.8	40.1	37.3	43.2	49.8	54.3

R/L	47+10.5m, 22.5t配重					
	0°		15°		30°	
	起重量	起升高度	起重量	起升高度	起重量	起升高度
11						
12	5.50	55.8				
14	4.94	55.5	4.05	55.2		
16	4.69	54.9	3.95	54.7	3.73	53.9
18	4.54	54.2	3.95	54	3.59	53.3
20	4.54	53.5	3.86	53.3	3.32	52.5
22	4.44	52.7	3.64	52.5	3.14	51.7
24	4.13	51.7	3.41	51.5	2.95	50.8
26	3.83	50.7	3.18	50.5	2.82	49.7
28	3.57	49.6	3.00	49.4	2.73	48.6
30	3.27	48.4	2.86	48.2	2.59	47.3
32	2.8	47.1	2.68	46.9	2.30	46
34	2.4	45.6	2.59	45.4	2.41	44.5
36	2	44	2.2	43.8	2.3	42.8
38	1.7	42.3	1.8	42	1.9	41
40	1.4	40.4	1.5	40.1	1.6	39
42	1.1	38.3	1.2	38	1.3	36.8
44	0.9	36	1	35.6	1.1	34.4
46	0.7	33.3	0.8	32.9	0.8	31.6
48			0.6	29.9	0.6	28.5

起重工况性能表 Lifting Performance Table

47+17.5m, 22.5t配重

R/L	0°		15°		30°	
	起重量	起升高度	起重量	起升高度	起重量	起升高度
14	3.3	62.1				
16	2.9	61.5	2.4	61.1		
18	2.7	60.9	2.2	60.6		
20	2.45	60.2	2.1	59.8		8.6
22	2.2	59.4	1.95	59	1.6	57.8
24	2.05	58.5	1.85	58.1	1.55	56.8
26	1.9	57.5	1.75	57.1	1.5	55.8
28	1.75	56.5	1.65	56.1	1.45	54.8
30	1.7	55.3	1.55	54.9	1.4	53.6
32	1.6	54.1	1.55	53.7	1.35	52.3
34	1.45	52.8	1.4	52.3	1.3	50.9
36	1.35	51.3	1.35	50.9	1.25	49.4
38	1.3	49.7	1.3	49.3	1.2	47.7
40	1.25	48	1.25	47.6	1.15	45.9
42	1.1	46.2	1.2	45.7	1.15	44
44	0.9	44.2	1.1	43.6	1.1	41.9
46	0.7	42	0.9	41.4	1	39.5
48			0.7	38.9	0.8	36.9
50					0.6	34.1

(4)、主臂工况，履带全伸，吊载行驶

履带全伸，配重22.5t，带载行驶

R/L	12.2	16.5	20.9	27.4
3	52.5			
4	47.6	42.7		
5	35.21	38.5	29.4	
6	25.2	29.12	27.3	19.2
7	19.32	21.63	21.49	19.2
8	15.47	17.01	16.8	17.64
9	12.74	13.79	13.65	14.35
10		11.41	11.27	11.97
12		9.66	9.52	10.22
14		6.9	7	7.63
16		5.32	5.32	5.95
18			3.9	4.69
20				3.71
22				3.01
倍率	9	7	4	4
最大仰角	68.7	73.4	74.8	77.3
最小仰角	25.4	42.8	40.1	37.3

起重工况性能表 Lifting Performance Table

XGC75T

(5)、臂端滑轮工况，履带全伸，吊载行驶

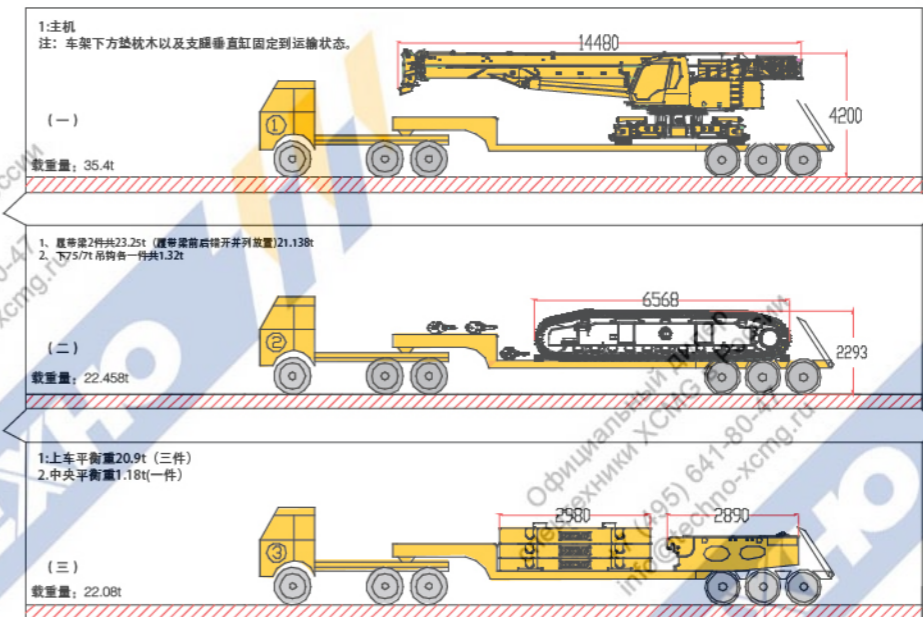
履带全伸，配重22.5t，带载行驶

R/L	12.2	16.5	20.9	27.4
3	6.5			
4	6.5	6.5		
5	6.5	6.5	6.5	
6	6.5	6.5	6.5	6.5
7	6.5	6.5	6.5	6.5
8	6.5	6.5	6.5	6.5
9	6.5	6.5	6.5	6.5
10		6.5	6.5	6.5
12		6.5	6.5	6.5
14		6.5	6.5	6.5
16			5.3	6
18			3.9	4.7
20				3.7
22				3
倍率		1		1
最大仰角	68.7	73.4	74.8	77.3
最小仰角	25.4	42.8	40.1	37.3

说明:

- 表中给定数值是在地面坚实、平整的状态下，起重机的额定起重量。表中工作幅度为吊载后的实际幅度。
- 主臂臂长≤27.4m时，整机可带载行走，其余主臂工况以及副臂工况不允许带载和空载行走。
- 带载行驶时要求履带必须为全伸状态。
- 主机空载时，仅基本臂12.2m时可高速行驶；臂长≤27.4m时，主机可低速（带载+空载）行走，其余臂长工况禁止行走。

整机运输方案 Transport Planning



备注:

- 图中尺寸均为设计尺寸，由于制造误差，可能稍有不同。
- 运输时主机和履带梁前后应该加垫木，防止在运输过程中发生滑动。
- 以上零部件运输尺寸为示意图，未按比例绘制，不包含包装。
- 图示高度尺寸，含板车高度(1m)和枕木高度(150mm)。

Note:

- The dimension in the diagram is design dimension which will be slightly different according to manufacturing error.
- Place wood block in front and behind track frame to prevent slide during transport.
- The transport dimension is sketch map, not drawn in proportion, and the dimension on the diagram is design value without package.